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# Casson's $\lambda$ -invariant and its application

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A. Casson [C1] defined an integer valued invariant  $\lambda(M)$  for an oriented homology 3-sphere  $M$ .

We give a sum formula to calculate Casson's  $\lambda$ -invariant for an oriented homology 3-sphere which is constructed by gluing two knot exteriors in homology 3-spheres with some diffeomorphism between their boundaries. Our result is just the  $\lambda$ -invariant version of C. Gordon's theorem [G1. Theorem 2] for  $\mu$ -invariant.

## §1. Casson's $\lambda$ -invariant.

Casson proved the following theorem.

Theorem 1 (A. Casson).

Let  $M$  be an oriented homology 3-sphere. There exist an integer valued invariant  $\lambda(M)$  with the following properties.

- (1) If  $\pi_1(M) = 1$ , then  $\lambda(M) = 0$ .
- (2)  $\lambda(M) = -\lambda(-M)$ , where  $-M$  denotes  $M$  with the opposite orientation.
- (3) Let  $K$  be a knot in  $M$  and  $(K_n; M)$  be the oriented homology 3-sphere obtained by performing  $1/n$ -Dehn surgery on  $M$  along  $K$ ,  $n \in \mathbb{Z}$ .  $\lambda(K_{n+1}; M) - \lambda(K_n; M)$  is determined independently to  $n$ .
- (4)  $\lambda(M)$  reduces, mod 2, to the Rohlin invariant  $\mu(M)$ .

By the property (3),  $\lambda'(K;M) = \lambda(K_{n+1};M) - \lambda(K_n;M)$  is well defined. By the fact that  $(K_0;M) = M$  and the induction on  $n$ ,

Corollary 2.  $\lambda(K_n;M) = \lambda(M) + n \lambda'(K;M)$ .

Let  $\Delta_{K;M}(t)$  be the normalized Alexander polynomial of a knot  $K$  in  $M$ . "normalized" means that the followings hold,

- (1)  $\Delta_{K;M}(1) = 1$ ,
- (2)  $\Delta_{K;M}(t) = \Delta_{K;M}(t^{-1})$ .

Moreover, let  $V$  be a  $2h \times 2h$  Seifert matrix of  $K$ , then the normalized Alexander polynomial is given as follows.

$$\Delta_{K;M}(t) = t^{-h} \det(V - tV^T).$$

Casson related  $\lambda'(K;M)$  to the above classical invariant of  $K$  as follows.

Theorem 3 (A. Casson).  $\lambda'(K;M) = \frac{1}{2} \Delta''_{K;M}(1)$ ,

where  $\Delta''_{K;M}(t)$  is the second derivative of normalized Alexander polynomial of  $K$ .

Corollary 2 and Theorem 3 are useful to calculate Casson's  $\lambda$ -invariant of an oriented homology 3-sphere. For example, we have the following.

Example.  $(\Sigma(p, q, pqr \pm 1)) = -r(p^2 - 1)(q^2 - 1)/24$ ,

where  $\Sigma(p, q, pqr \pm 1)$  is the Brieskorn homology sphere and  $p, q, r$  are pairwise coprime integers  $\geq 2$ .

## §2. A sum formula for Casson's $\lambda$ -invariant.

To give the formula precisely, we need some notations.

We study oriented homology 3-spheres which are constructed by C. Gordon [G1]. Let  $M_i$  be an oriented homology 3-sphere and  $K_i$  be an oriented knot in  $M_i$  with the exterior  $X_i$ , for  $i = 1, 2$ . We always identify  $\partial X_i$  with  $S^1 \times \partial D^2$  and parametrize it by an angular coordinate  $(\theta, \varphi)$ . If  $A$  be a  $2 \times 2$  integral matrix  $\begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$  with  $\det A = -1$ , then  $A$  defines an orientation reversing diffeomorphism  $h; \partial X_1 \rightarrow \partial X_2$  by  $h(\theta, \varphi) = (\alpha\theta + \beta\varphi, \gamma\theta + \delta\varphi)$ . We denote the naturally oriented closed 3-manifold obtained by gluing two knot exteriors with  $h$ ,  $X_1 \cup_h X_2$  as  $M(K_1, K_2; A)$  or  $M(K_1, K_2; \alpha, \beta, \gamma, \delta)$ . By the explicit computation of the first homology group of  $M(K_1, K_2; A)$ , it is known that  $M(K_1, K_2; \alpha, \beta, \gamma, \delta)$  becomes a homology 3-sphere if and only if  $|\gamma| = 1$ . Hereafter, we assume always this. Since  $\det A = \alpha\delta - \beta\gamma = -1$  and  $|\gamma| = 1$ ,  $\beta = \pm(\alpha\delta + 1)$ , so it is determined by  $\alpha, \delta$  and the sign  $\varepsilon$ . Hence we denote the homology 3-sphere obtained this construction by  $M^\varepsilon(K_1, K_2; \alpha, \delta)$ .

Our result is the following.

Theorem 4.

$$\lambda(M^\varepsilon(K_1, K_2; \alpha, \delta)) = \lambda(M_1) + \lambda(M_2) - \varepsilon\delta\lambda'(K_1; M_1) + \varepsilon\alpha\lambda'(K_2; M_2).$$

Remarks.

(1) It is known that  $\lambda'(K; M)$  reduces, mod 2, to the Arf invariant  $c(K; M)$ . The theorem above is  $\lambda$ -invariant version of Gordon's formula [G1, Theorem 2] for  $\mu$ -invariant of the oriented homology 3-sphere  $M^\varepsilon(K_1, K_2; \alpha, \delta)$ .

(2) Using Corollary 2, the formula in the theorem is also denoted as follows,

$$\lambda(M^\varepsilon(K_1, K_2; \alpha, \delta)) = \lambda((K_1)_{-\varepsilon\delta}; M_1) + \lambda((K_2)_{\varepsilon\alpha}; M_2).$$

This is the reason why we call it "a sum formula for Casson's  $\lambda$ -invariant".

(3) S. Akbult and J. McCarthy obtained the same formula independently.

### §3. Outline of the proof.

Changing the gluing map, we have the following topological lemma.

Lemma 5.  $M = M^{\epsilon}(K_1, K_2; \alpha, \delta) = ((K_1^* \# K_2^*)_{\mp 1}; N_1 \# N_2)$ , where  $K_i^*$  is a 0-parallel knot of  $K_i$  in  $M_i$  and  $N_i = ((K_i^*)_{n_i}; M_i)$ , for  $i = 1, 2$ , and  $n_1 \mp 1 = -\epsilon\delta$ ,  $n_2 \mp 1 = \epsilon\alpha$ .

We omit the proof and refer to [FM] and [G2].

Next we need a couple of properties of  $\lambda$  and  $\lambda'$ .

Since the Seifert matrix of a connected sum of two knots is a block sum of Seifert matrices,

$$\Delta_{K_1 \# K_2; M_1 \# M_2}(t) = \Delta_{K_1; M_1}(t) \cdot \Delta_{K_2; M_2}(t).$$

By the fact that  $\Delta'_{K; M}(1) = 0$  and computing second derivatives of the above equation, we have,

Lemma 6.  $\lambda'(K_1 \# K_2; M_1 \# M_2) = \lambda'(K_1; M_1) + \lambda'(K_2; M_2)$ .

Considering a framed link description of  $M_1$  such that the corresponding framed link satisfy the condition that linking numbers of any two components are zero and using Lemma 6,

Lemma 7.  $\lambda(M_1 \# M_2) = \lambda(M_1) + \lambda(M_2)$ .

Let  $M$  be an oriented homology 3-sphere and  $K$  be a knot in  $M$ . Consider two disjoint two simple closed curves  $a, b$  in  $M - K$ . Let  $N$  be  $(K_n; M)$ . Then the following fact is known L.

$$lk_N(a, b) = lk_M(a, b) - n \cdot lk_M(a, K) + lk_M(b, K),$$

where  $a$  and  $b$  can be seen naturally curves in  $N$ .

Using this fact, the next follows.

Lemma 8. Let  $K$  be a knot in an oriented homology 3-sphere  $M$  and  $K^*$  be a zero parallel knot of  $K$  in  $M$ . Let  $N = (K_n; M)$ , then

$$\lambda'(K^*; N) = \lambda'(K; M).$$

We prove Theorem 4 as follows:

By Lemma 5 and Corollary 2,

$$\lambda(M^{\#}(K_1, K_2; \alpha, \delta)) = \lambda(N_1 \# N_2) \mp \lambda'(K_1^* \# K_2^*; N_1 \# N_2),$$

by Lemma 6 and Lemma 7,

$$= \lambda(N_1) + \lambda(N_2) \mp \lambda'(K_1^*; N_1) \mp \lambda'(K_2^*; N_2),$$

by Corollary 2 and Lemma 8,

$$= \lambda(M_1) + (n_1 \mp 1) \lambda'(K_1; M_1) \\ + \lambda(M_2) + (n_2 \mp 1) \lambda'(K_2; M_2),$$

using the definition of  $n_i$  for  $i = 1, 2$ , we have the desired formula.

#### 4. Concluding remark.

By analogous consideration of L. Siebenmann [S], we can prove the following.

Theorem 9. Let  $M$  be an oriented homology 3-sphere and  $T$  be a 2-torus family <sup>which</sup>  $\Lambda$  determine a graph  $\Gamma$ . Then

$$\lambda(M) = \sum_{v \in \Gamma^{(0)}} \lambda(M(v)_+).$$

From the view point of this theorem, it seems worthful to compile many data of Casson's  $\lambda$ -invariant of oriented homology 3-spheres. Hence we have the following problem.

Problem. Let  $M$  be a graph homology 3-sphere in the sense of Waldhausen [W]. Give a formula to calculate  $\lambda(M)$  automatically from the corresponding weighted graph of  $M$ .

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